

Mathematics B  
Master Solution Alternative Date Exam  
Spring Semester 2017

Prof. Dr. Enrico De Giorgi\*

7 February 2018

---

\*Faculty of Mathematics and Statistics, University St. Gallen, Bodanstrasse 6, 9000 St. Gallen, Switzerland,  
email: enrico.degiorgi@unisg.ch.

## Part I: Open Questions

### Exercise 1

(a) (7 points)

The necessary conditions for maxima, minima or saddle points  $(x^*, y^*)$  of  $f$  are

$$\begin{cases} f_x(x^*, y^*) = 0 \\ f_y(x^*, y^*) = 0 \end{cases} .$$

We thus compute the first order partial derivatives of  $f$  and we obtain

$$\begin{aligned} f_x(x, y) &= 2ay + 4x^3, \\ f_y(x, y) &= 2ay + 2ax. \end{aligned}$$

It follows that:

$$\begin{cases} f_x(x^*, y^*) = 0 \\ f_y(x^*, y^*) = 0 \end{cases} \Leftrightarrow \begin{cases} 2ay^* + 4(x^*)^3 = 0 \\ 2ay^* + 2ax^* = 0 \end{cases} .$$

From  $2ay^* + 2ax^* = 0$  we obtain

$$x^* = -y^*.$$

We plug this latter result into  $2ay^* + 4(x^*)^3 = 0$  and we find

$$\begin{aligned} 4(x^*)^3 = 2ax^* &\Leftrightarrow 2x^*(2(x^*)^2 - a) = 0 \\ &\Leftrightarrow x^* \in \left\{ -\sqrt{\frac{a}{2}}, 0, \sqrt{\frac{a}{2}} \right\}. \end{aligned}$$

Using that  $y^* = -x^*$ , we obtain three stationary points for  $f$ :

$$P_1 = (0, 0),$$

$$P_2 = \left( \sqrt{\frac{a}{2}}, -\sqrt{\frac{a}{2}} \right),$$

and

$$P_3 = \left( -\sqrt{\frac{a}{2}}, \sqrt{\frac{a}{2}} \right).$$

Next, we verify the sufficient conditions: if  $(x^*, y^*)$  satisfies the necessary conditions, then the following holds:

$$\begin{cases} f_{xx}(x^*, y^*) > 0 \\ f_{yy}(x^*, y^*) > 0 \\ f_{xx}(x^*, y^*) f_{yy}(x^*, y^*) - (f_{xy}(x^*, y^*))^2 > 0 \end{cases} \Rightarrow (x^*, y^*) \text{ is a minimum,}$$

$$\begin{cases} f_{xx}(x^*, y^*) < 0 \\ f_{yy}(x^*, y^*) < 0 \\ f_{xx}(x^*, y^*) f_{yy}(x^*, y^*) - (f_{xy}(x^*, y^*))^2 > 0 \end{cases} \Rightarrow (x^*, y^*) \text{ is a maximum,}$$

and

$$f_{xx}(x^*, y^*) f_{yy}(x^*, y^*) - (f_{xy}(x^*, y^*))^2 < 0 \Rightarrow (x^*, y^*) \text{ is a saddle point.}$$

For the sufficient conditions we need the second order partial derivatives of  $f$ . We have:

$$\begin{aligned} f_{xx}(x, y) &= 12x^2, \\ f_{yy}(x, y) &= 2a, \\ f_{xy}(x, y) &= 2a. \end{aligned}$$

It follows that:

$$f_{xx}(x^*, y^*) f_{yy}(x^*, y^*) - (f_{xy}(x^*, y^*))^2 = 24(x^*)^2 a - 4a^2.$$

For  $P_1 = (0, 0)$  we have:

$$f_{xx}(0, 0) f_{yy}(0, 0) - (f_{xy}(0, 0))^2 = -4a^2 < 0.$$

Therefore,  $P_1 = (0, 0)$  is a saddle point.

For  $P_2 = (\sqrt{\frac{a}{2}}, -\sqrt{\frac{a}{2}})$  we have (note that  $a \in \mathbb{R}_{++}$ ):

$$\left\{ \begin{array}{l} f_{xx} \left( \sqrt{\frac{a}{2}}, -\sqrt{\frac{a}{2}} \right) = 6a > 0 \\ f_{yy} \left( \sqrt{\frac{a}{2}}, -\sqrt{\frac{a}{2}} \right) = 2a > 0 \\ f_{xx} \left( \sqrt{\frac{a}{2}}, -\sqrt{\frac{a}{2}} \right) f_{yy} \left( \sqrt{\frac{a}{2}}, -\sqrt{\frac{a}{2}} \right) - (f_{xy} \left( \sqrt{\frac{a}{2}}, -\sqrt{\frac{a}{2}} \right))^2 = 8a^2 > 0 \end{array} \right. .$$

Therefore,  $P_2 = (\sqrt{\frac{a}{2}}, -\sqrt{\frac{a}{2}})$  is a local minimum.

For  $P_3 = (-\sqrt{\frac{a}{2}}, \sqrt{\frac{a}{2}})$  we have (note that  $a \in \mathbb{R}_{++}$ ):

$$\left\{ \begin{array}{l} f_{xx} \left( -\sqrt{\frac{a}{2}}, \sqrt{\frac{a}{2}} \right) = 6a > 0 \\ f_{yy} \left( -\sqrt{\frac{a}{2}}, \sqrt{\frac{a}{2}} \right) = 2a > 0 \\ f_{xx} \left( -\sqrt{\frac{a}{2}}, \sqrt{\frac{a}{2}} \right) f_{yy} \left( -\sqrt{\frac{a}{2}}, \sqrt{\frac{a}{2}} \right) - (f_{xy} \left( -\sqrt{\frac{a}{2}}, \sqrt{\frac{a}{2}} \right))^2 = 8a^2 > 0 \end{array} \right. .$$

Therefore,  $P_3 = (-\sqrt{\frac{a}{2}}, \sqrt{\frac{a}{2}})$  is a local minimum.

**(b) (7 points)**

We apply the Lagrange method. First of all we define the Lagrange function:

$$\begin{aligned} F(x, y, \lambda) &= f(x, y) + \lambda \varphi(x, y) \\ &= 2x^2 + y^2 + \lambda(x^2 - axy + by^2 + 15). \end{aligned}$$

The necessary conditions for constrained extreme points of  $f$ , given the constraint  $\varphi(x, y) = 0$ , are the so-called Lagrange conditions:

$$F_x(x, y, \lambda) = 0 \Rightarrow 4x + \lambda(2x - ay) = 0, \quad (\text{I})$$

$$F_y(x, y, \lambda) = 0 \Rightarrow 2y + \lambda(-ax + 2by) = 0, \quad (\text{II})$$

$$F_\lambda(x, y, \lambda) = 0 \Rightarrow x^2 - axy + by^2 + 15 = 0. \quad (\text{III})$$

Therefore, in order that  $(x, y) = (1, 2)$  is a constrained extreme point of  $f$ , we must have:

$$F_x(1, 2, \lambda) = 0 \Rightarrow 4 + \lambda(2 - 2a) = 0, \quad (\text{IV})$$

$$F_y(1, 2, \lambda) = 0 \Rightarrow 4 + \lambda(-a + 4b) = 0, \quad (\text{V})$$

$$F_\lambda(1, 2, \lambda) = 0 \Rightarrow 1 - 2a + 4b + 15 = 0. \quad (\text{VI})$$

From (IV) we obtain:

$$\lambda = \frac{4}{2a - 2}. \quad (\text{VII})$$

From (V) we obtain:

$$\lambda = \frac{4}{a - 4b}. \quad (\text{VIII})$$

Equations (VII) and (VIII) imply that:

$$\frac{4}{2a - 2} = \lambda = \frac{4}{a - 4b} \Leftrightarrow 2a - 2 = a - 4b \Leftrightarrow a = 2 - 4b.$$

We plug this result into (VI) and we have:

$$1 - 2(2 - 4b) + 4b + 15 = 0 \Leftrightarrow -12b = 12 \Leftrightarrow b = -1 \Rightarrow a = 6.$$

**(c) (5 points)**

First of all, applying the property  $\ln(x^r) = r \ln(x)$  of the logarithm, we get:

$$\int_1^e x^2 \ln(\sqrt{x}) dx = \frac{1}{2} \int_1^e x^2 \ln(x) dx.$$

We compute the indefinite integral  $\int x^2 \ln(x) dx$  using integration by parts. Let

$$u'(x) = x^2 \quad \text{and} \quad v(x) = \ln(x).$$

Then,

$$u = \frac{1}{3} x^3 \quad \text{and} \quad v'(x) = \frac{1}{x}.$$

It follows that:

$$\begin{aligned} \int \underbrace{x^2}_{=u'(x)} \underbrace{\ln(x)}_{=v(x)} dx &= \underbrace{\frac{1}{3} x^3}_{=u(x)} \underbrace{\ln(x)}_{=v(x)} - \int \underbrace{\frac{1}{3} x^3}_{=u(x)} \underbrace{\frac{1}{x}}_{=v'(x)} dx \\ &= \frac{1}{3} x^3 \ln(x) - \frac{1}{3} \int x^2 dx \\ &= \frac{1}{3} x^3 \ln(x) - \frac{1}{9} x^3 + C, \quad C \in \mathbb{R} \\ &= \frac{1}{3} x^3 \left( \ln(x) - \frac{1}{3} \right) + C. \end{aligned}$$

We now compute the definite integral:

$$\begin{aligned} \int_1^e x^2 \ln(\sqrt{x}) dx &= \frac{1}{2} \left[ \frac{1}{3} x^3 \left( \ln(x) - \frac{1}{3} \right) \right]_1^e \\ &= \frac{1}{6} e^3 \left( 1 - \frac{1}{3} \right) - \frac{1}{6} \left( 0 - \frac{1}{3} \right) \\ &= \frac{2e^3 + 1}{18} \approx 2.287. \end{aligned}$$

(d) (6 points)

We solve the indefinite integral  $\int \frac{e^x + x e^x}{(x e^x)^3} dx$  using the substitution rule. Let  $u = x e^x$ , then:

$$\frac{du}{dx} = e^x + x e^x$$

and

$$(e^x + x e^x) dx = du.$$

We obtain:

$$\int \frac{e^x + x e^x}{(x e^x)^3} dx = \int \frac{1}{u^3} du = -\frac{1}{2u^2} + C = -\frac{1}{2(x e^x)^2} + C.$$

We now compute the improper integral:

$$\begin{aligned} \int_1^{\infty} \frac{e^x + x e^x}{(x e^x)^3} dx &= \lim_{b \rightarrow \infty} \int_1^b \frac{e^x + x e^x}{(x e^x)^3} dx \\ &= \lim_{b \rightarrow \infty} \left[ -\frac{1}{2(x e^x)^2} \right]_1^b \\ &= \lim_{b \rightarrow \infty} \left[ -\frac{1}{2(b e^b)^2} + \frac{1}{2e^2} \right] \\ &= \lim_{b \rightarrow \infty} \underbrace{\left[ -\frac{1}{2(b e^b)^2} \right]}_{\rightarrow 0} + \frac{1}{2e^2} \\ &= \frac{1}{2e^2} \approx 0.0677 \end{aligned}$$

**Exercise 2**

(a) (4 points)

We have to prove the following:

$$C^T = C.$$

We obtain:

$$\begin{aligned} C^T &= [B^{-1} A A^T (B^T)^{-1}]^T \\ &= [(B^T)^{-1}]^T (A^T)^T A^T (B^{-1})^T \\ &= [(B^T)^T]^{-1} A A^T (B^T)^{-1} \\ &= B^{-1} A A^T (B^T)^{-1} \\ &= C. \end{aligned}$$

(b) (4 points)

The direction of the steepest descent of  $f$  at the point  $(x_0, y_0) = (-1, \pi)$  is given by the vector

$$\mathbf{b} = \begin{pmatrix} 2 \\ -1 \end{pmatrix}$$

if and only if

$$\lambda \mathbf{b} = \mathbf{grad} f(-1, \pi)$$

for some  $\lambda < 0$ .

We have:

$$\mathbf{grad} f(x, y) = \begin{pmatrix} f_x(x, y) \\ f_y(x, y) \end{pmatrix} = \begin{pmatrix} \sin(y) + \frac{a}{x+2} + \frac{y}{\pi} \\ x \cos(y) + \frac{x}{\pi} \end{pmatrix}.$$

It follows that:

$$\mathbf{grad} f(-1, \pi) = \begin{pmatrix} a + 1 \\ 1 - \frac{1}{\pi} \end{pmatrix}.$$

Therefore, we have:

$$\begin{aligned} \lambda \mathbf{b} &= \mathbf{grad} f(-1, \pi) \\ \Leftrightarrow \lambda \begin{pmatrix} 2 \\ -1 \end{pmatrix} &= \begin{pmatrix} a + 1 \\ 1 - \frac{1}{\pi} \end{pmatrix}. \end{aligned}$$

It follows (2<sup>nd</sup> component) that  $\lambda = \frac{1}{\pi} - 1 < 0$  and

$$a + 1 = 2 \left( \frac{1}{\pi} - 1 \right) \Leftrightarrow a = \frac{2}{\pi} - 3 \approx -2.3634.$$

**(c) (3 points)**

Since we have three linearly independent equations, it holds for the dimension of  $V$  that

$$\dim(V) = 5 - 3 = 2.$$

In particular,  $x_4$  and one more variable are free variables. We choose

$$x_1 = t, \quad x_4 = s.$$

We now solve for the other variables  $x_2, x_3, x_5$ :

$$\begin{aligned} x_1 + x_2 = 0 &\Rightarrow x_2 = -x_1 = -t, \\ x_1 + 5x_2 - 2x_3 = 0 &\Rightarrow 2x_3 = x_1 + 5x_2 = -4t \Rightarrow x_3 = -2t, \\ x_1 - x_3 + x_5 = 0 &\Rightarrow x_5 = -x_1 + x_3 = -3t. \end{aligned}$$

Therefore, we get the following basis of  $V \subset \mathbb{R}^5$ :

$$\mathcal{B}(V) = \left\{ \mathbf{b}_1 = \begin{pmatrix} 1 \\ -1 \\ -2 \\ 0 \\ -3 \end{pmatrix}, \mathbf{b}_2 = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 0 \end{pmatrix} \right\}$$

**(d) (6 points)**

$\lambda$  is an eigenvalue of  $M$  if and only if  $\det(M - \lambda I) = 0$ . We have:

$$\begin{aligned} \det(M - \lambda I) &= \left| \begin{pmatrix} -\lambda & 3 & 0 \\ 1 & 2 - \lambda & 0 \\ -5a & 5 & 4 - \lambda \end{pmatrix} \right| \\ &= -\lambda(2 - \lambda)(4 - \lambda) - 3(4 - \lambda) \\ &= (4 - \lambda)(\lambda^2 - 2\lambda - 3) \\ &= (4 - \lambda)(\lambda - 3)(\lambda + 1) \end{aligned}$$

and thus

$$\det(M - \lambda I) = 0 \Leftrightarrow \lambda \in \{-1, 3, 4\}.$$

In particular,  $\lambda = 3$  is an eigenvalue of  $M$ .

We now compute the eigenvectors corresponding to the eigenvalue  $\lambda = 3$ . The vector  $\mathbf{x} = (x_1, x_2, x_3)^T$  is an eigenvector of  $M$  associated with the eigenvalue  $\lambda$  if and only if  $(M - \lambda I)\mathbf{x} = \mathbf{0}$ .



For  $\lambda = 3$  we have (applying the Gauss method):

$$\begin{aligned}
 (M - 3I, \mathbf{0}) &= \left( \begin{array}{ccc|c} x_1 & x_2 & x_3 & \\ -3 & 3 & 0 & 0 \\ 1 & -1 & 0 & 0 \\ -5a & 5 & 1 & 0 \end{array} \right) : (-3) \\
 &\rightarrow \left( \begin{array}{ccc|c} 1 & -1 & 0 & 0 \\ 1 & -1 & 0 & 0 \\ -5a & 5 & 1 & 0 \end{array} \right) \begin{array}{l} \\ +(I) \\ +5a(I) \end{array} \\
 &\rightarrow \left( \begin{array}{ccc|c} 1 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 5-5a & 1 & 0 \end{array} \right) ,
 \end{aligned}$$

i.e.:

$$\begin{aligned}
 x_1 - x_2 &= 0, \\
 (5 - 5a)x_2 + x_3 &= 0.
 \end{aligned}$$

We choose  $x_2 = t$  and obtain:

$$\begin{aligned}
 x_1 &= x_2 = t, \\
 x_2 &= t, \\
 x_3 &= (5a - 5)x_2 = (5a - 5)t.
 \end{aligned}$$

Therefore, the eigenspace, i.e. the set of all eigenvalues plus the vector  $\mathbf{v} = \mathbf{0}$ , is given by

$$V_{(\lambda=3)} = \left\{ \mathbf{x} \in \mathbb{R}^3 : \mathbf{x} = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = t \begin{pmatrix} 1 \\ 1 \\ 5a - 5 \end{pmatrix} ; t \in \mathbb{R} \right\}.$$

(e) (6 points)

We apply the Gauss method:

$$\begin{aligned}
 & \begin{pmatrix} x_1 & x_2 & x_3 & | & \\ 4 & 0 & 4 & | & 8 \\ 12 & 16 & 8 & | & 36 + 4r \\ 0 & 1 & -2 & | & s \\ 3 & 2 & 3 & | & 9 - 2r + s \\ 1 & 1 & 1 & | & 3 \end{pmatrix} : 4 & \rightarrow & \begin{pmatrix} x_1 & x_2 & x_3 & | & \\ 1 & 0 & 1 & | & 2 \\ 12 & 16 & 8 & | & 36 + 4r \\ 0 & 1 & -2 & | & s \\ 3 & 2 & 3 & | & 9 - 2r + s \\ 1 & 1 & 1 & | & 1 \end{pmatrix} \begin{matrix} \\ -12(I) \\ \\ -3(I) \\ -I \end{matrix} \\
 & \rightarrow \begin{pmatrix} x_1 & x_2 & x_3 & | & \\ 1 & 0 & 1 & | & 2 \\ 0 & 16 & -4 & | & 12 + 4r \\ 0 & 1 & -2 & | & s \\ 0 & 2 & 0 & | & 3 - 2r + s \\ 0 & 1 & 0 & | & 1 \end{pmatrix} \begin{matrix} \\ \\ (II) \leftrightarrow (V) \\ \\ \\ \end{matrix} \rightarrow \begin{pmatrix} x_1 & x_2 & x_3 & | & \\ 1 & 0 & 1 & | & 2 \\ 0 & 1 & 0 & | & 1 \\ 0 & 1 & -2 & | & s \\ 0 & 2 & 0 & | & 3 - 2r + s \\ 0 & 16 & -4 & | & 12 + 4r \end{pmatrix} \begin{matrix} \\ \\ -(II) \\ -2(II) \\ -16(II) \end{matrix} \\
 & \rightarrow \begin{pmatrix} x_1 & x_2 & x_3 & | & \\ 1 & 0 & 1 & | & 2 \\ 0 & 1 & 0 & | & 1 \\ 0 & 0 & -2 & | & s - 1 \\ 0 & 0 & 0 & | & 1 - 2r + s \\ 0 & 0 & -4 & | & -4 + 4r \end{pmatrix} : (-2) & \rightarrow & \begin{pmatrix} x_1 & x_2 & x_3 & | & \\ 1 & 0 & 1 & | & 2 \\ 0 & 1 & 0 & | & 1 \\ 0 & 0 & 1 & | & \frac{1}{2} - \frac{1}{2}s \\ 0 & 0 & 0 & | & 1 - 2r + s \\ 0 & 0 & -4 & | & -4 + 4r \end{pmatrix} \begin{matrix} \\ \\ \\ -(III) \\ -4(III) \end{matrix} \\
 & \rightarrow \begin{pmatrix} x_1 & x_2 & x_3 & | & \\ 1 & 0 & 0 & | & \frac{3}{2} + \frac{1}{2}s \\ 0 & 1 & 0 & | & 1 \\ 0 & 0 & 1 & | & \frac{1}{2} - \frac{1}{2}s \\ 0 & 0 & 0 & | & 1 - 2r + s \\ 0 & 0 & 0 & | & -2 + 4r - 2s \end{pmatrix} \begin{matrix} \\ \\ \\ -(III) \\ -4(III) \end{matrix}
 \end{aligned}$$

Therefore, the system of equation is solvable if and only if:

$$1 - 2r + s = 0 \wedge -2 + 4r - 2s = 0 \Rightarrow s = 2r - 1.$$

Hence an unique solution exists for  $s = 2r - 1$ ,  $r \in \mathbb{R}$  and corresponds to:

$$\mathbf{x} = \begin{pmatrix} \frac{3}{2} + \frac{1}{2}s \\ 1 \\ \frac{1}{2} - \frac{1}{2}s \end{pmatrix} = \begin{pmatrix} r + 1 \\ 1 \\ 1 - r \end{pmatrix}.$$

## Part II: Multiple-choice Questions

### Exercise 3

|            | (a)                                 | (b)                                 | (c)                                 | (d)                                 |
|------------|-------------------------------------|-------------------------------------|-------------------------------------|-------------------------------------|
| Question 1 | <input type="checkbox"/>            | <input type="checkbox"/>            | <input checked="" type="checkbox"/> | <input type="checkbox"/>            |
| Question 2 | <input type="checkbox"/>            | <input type="checkbox"/>            | <input type="checkbox"/>            | <input checked="" type="checkbox"/> |
| Question 3 | <input type="checkbox"/>            | <input checked="" type="checkbox"/> | <input type="checkbox"/>            | <input type="checkbox"/>            |
| Question 4 | <input type="checkbox"/>            | <input type="checkbox"/>            | <input type="checkbox"/>            | <input checked="" type="checkbox"/> |
| Question 5 | <input checked="" type="checkbox"/> | <input type="checkbox"/>            | <input type="checkbox"/>            | <input type="checkbox"/>            |
| Question 6 | <input type="checkbox"/>            | <input checked="" type="checkbox"/> | <input type="checkbox"/>            | <input type="checkbox"/>            |
| Question 7 | <input checked="" type="checkbox"/> | <input type="checkbox"/>            | <input type="checkbox"/>            | <input type="checkbox"/>            |
| Question 8 | <input type="checkbox"/>            | <input type="checkbox"/>            | <input type="checkbox"/>            | <input checked="" type="checkbox"/> |

**Q1.** (c). The constraint  $\varphi(x, y) = \frac{x^2}{4} + \frac{y^2}{25} - 1 = 0$  corresponds to an ellipse with centre  $(0, 0)$  and semi-axes 2 and 5. The function  $f(x, y) = -x$  takes its minimum if  $x$  gets maximal. The point on the ellipse with the largest  $x$ -value is  $P = (2, 0)$ . Note that the point  $P = (3, 1)$  does not fulfill the constraint.

**Q2.** (d). Since  $f(2) = -1 < 0$  for all  $a \in \mathbb{R}$ ,  $f$  cannot be a density function.

**Q3.** (b). Because  $\text{rg}(A) \leq \min\{6, 4\} = 4$  and  $\text{rg}(A) = \text{rg}(A^T)$ , only answer (b) can be true.

**Q4.** (d). There is no general relationship for the determinant of a sum of matrices.

**Q5.** (a). Because  $\det([\mathbf{a}, \mathbf{b}, \mathbf{c}]) = 0$ , the system of vectors  $\{\mathbf{a}, \mathbf{b}, \mathbf{c}\}$  is linearly dependent. In particular, we have  $\mathbf{a} + \mathbf{b} = \mathbf{c}$ . Therefore,  $\mathbf{d}$  is a linear combination of  $\mathbf{a}$ ,  $\mathbf{b}$  and  $\mathbf{c}$  if and only if it is a linear combination of  $\mathbf{a}$  and  $\mathbf{b}$ . This is true if and only if the system  $\{\mathbf{a}, \mathbf{b}, \mathbf{d}\}$  is linearly dependent, that is, if and only if

$$\det([\mathbf{a}, \mathbf{b}, \mathbf{d}]) = \left| \begin{pmatrix} 2 & -1 & -1 \\ 1 & 1 & 4 \\ 3 & 1 & t \end{pmatrix} \right| = 3t - 18 = 0 \Leftrightarrow t = 6.$$

We have:

$$\mathbf{a} + 3\mathbf{b} = \mathbf{d}.$$

**Q6.** (b). Because  $\text{rg}(A) \leq \text{rg}(A, \mathbf{b}) = 4$ , the system has a unique solution if and only if  $\text{rg}(A) = 4$  and no solution for  $\text{rg}(A) < 4$ .

**Q7.** (a). Let  $f(x) = \frac{x}{5} - \frac{2}{25} \ln(5x + 2) + C$ , for some  $C \in \mathbb{R}$ . We have:

$$f'(x) = \frac{1}{5} - \frac{2}{25} \frac{5}{5x + 2} = \frac{(5x + 2) - 2}{5(5x + 2)} = \frac{x}{5x + 2}.$$

Therefore,

$$\int \frac{x}{5x + 2} dx = \frac{x}{5} - \frac{2}{25} \ln(5x + 2) + C.$$

It can be easily shown that the functions in answers (b) and (c) are *no* antiderivatives of  $\frac{x}{5x+2}$ .

**Q8.** (d). We have

$$A \mathbf{b} = \begin{pmatrix} 3 & 4 \\ 1 & 3 \end{pmatrix} \begin{pmatrix} -4 \\ -2 \end{pmatrix} = \begin{pmatrix} -20 \\ -10 \end{pmatrix} = 5 \mathbf{b}.$$

Hence  $\mathbf{b}$  is an eigenvector of  $A$  corresponding to the eigenvalue  $\lambda = 5$  and it holds that

$$A^n \mathbf{b} = 5^n \mathbf{b} \text{ for all } n \in \mathbb{N}.$$

Therefore, (a) - (c) are wrong.

**Exercise 4**

|            | (a)                      | (b)                                 | (c)                                 | (d)                                 |
|------------|--------------------------|-------------------------------------|-------------------------------------|-------------------------------------|
| Question 1 | <input type="checkbox"/> | <input checked="" type="checkbox"/> | <input type="checkbox"/>            | <input type="checkbox"/>            |
| Question 2 | <input type="checkbox"/> | <input type="checkbox"/>            | <input checked="" type="checkbox"/> | <input type="checkbox"/>            |
| Question 3 | <input type="checkbox"/> | <input checked="" type="checkbox"/> | <input type="checkbox"/>            | <input type="checkbox"/>            |
| Question 4 | <input type="checkbox"/> | <input type="checkbox"/>            | <input type="checkbox"/>            | <input checked="" type="checkbox"/> |
| Question 5 | <input type="checkbox"/> | <input type="checkbox"/>            | <input checked="" type="checkbox"/> | <input type="checkbox"/>            |
| Question 6 | <input type="checkbox"/> | <input checked="" type="checkbox"/> | <input type="checkbox"/>            | <input type="checkbox"/>            |
| Question 7 | <input type="checkbox"/> | <input type="checkbox"/>            | <input type="checkbox"/>            | <input checked="" type="checkbox"/> |
| Question 8 | <input type="checkbox"/> | <input checked="" type="checkbox"/> | <input type="checkbox"/>            | <input type="checkbox"/>            |

**Q1.** (b). We have

$$\begin{aligned}
 \int_{-\infty}^1 e^{2x+1} dx &= \lim_{a \rightarrow -\infty} \left[ \frac{1}{2} e^{2x+1} \right]_a^1 \\
 &= \lim_{a \rightarrow -\infty} \left( \frac{e^3}{2} - \frac{e^{2a+1}}{2} \right) \\
 &= \frac{e^3}{2} - \underbrace{\lim_{a \rightarrow -\infty} \frac{e^{2a+1}}{2}}_{\rightarrow 0} \\
 &= \frac{e^3}{2}.
 \end{aligned}$$

**Q2.** (c). We have:

$$\mathbf{grad}f(x, y) = \begin{pmatrix} 2x \\ -\frac{1}{y} \end{pmatrix}.$$

$\mathbf{grad}f(t, t)$  is orthogonal to  $\mathbf{b}$  if and only if

$$\begin{aligned}
 \mathbf{grad}f(t, t) \cdot \mathbf{b} &= 0 \\
 \Leftrightarrow 2t - \frac{1}{t} &= 0 \\
 \Leftrightarrow t^2 &= \frac{1}{2} \\
 \stackrel{t \geq 0}{\Rightarrow} t &= \sqrt{\frac{1}{2}} = \frac{\sqrt{2}}{2}.
 \end{aligned}$$

**Q3.** (b). We apply the Gauss method:

$$A = \begin{pmatrix} 1 & 1 & -3 & 5 & 6 \\ -2 & -1 & 2 & 4 & 9 \\ 9 & 5 & -10 & 0 & 1 \\ 2 & 0 & 3 & -7 & 1 \end{pmatrix} \begin{matrix} +2(I) \\ -9(I) \\ -2(I) \end{matrix}$$

$$\begin{aligned} & \rightarrow \begin{pmatrix} 1 & 1 & -3 & 5 & 6 \\ 0 & 1 & -4 & 14 & 21 \\ 0 & -4 & 17 & -45 & -53 \\ 0 & -2 & 9 & -17 & -11 \end{pmatrix} \begin{array}{l} -(II) \\ \\ +4(II) \\ +2(II) \end{array} \\ & \rightarrow \begin{pmatrix} 1 & 0 & 1 & -9 & -15 \\ 0 & 1 & -4 & 14 & 21 \\ 0 & 0 & 1 & 11 & 31 \\ 0 & 0 & 1 & 11 & 31 \end{pmatrix} \begin{array}{l} -(III) \\ +4(III) \\ \\ -(III) \end{array} \\ A^* &= \begin{pmatrix} 1 & 0 & 0 & -20 & -46 \\ 0 & 1 & 0 & 58 & 145 \\ 0 & 0 & 1 & 11 & 31 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}. \end{aligned}$$

It follows that  $\text{rg}(A^*) = 3$  and thus  $\text{rg}(A) = \text{rg}(A^*) = 3$ .

**Q4.** (d). We apply the Gauss method:

$$\begin{aligned} (A|I) &= \left( \begin{array}{ccc|ccc} 1 & 1 & 1 & 1 & 0 & 0 \\ 0 & -1 & -1 & 0 & 1 & 0 \\ -1 & 0 & 1 & 0 & 0 & 1 \end{array} \right) \begin{array}{l} \\ :(-1) \\ +(I) \end{array} \\ &\rightarrow \left( \begin{array}{ccc|ccc} 1 & 1 & 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 & -1 & 0 \\ 0 & 1 & 2 & 1 & 0 & 1 \end{array} \right) \begin{array}{l} -(II) \\ \\ -(II) \end{array} \\ &\rightarrow \left( \begin{array}{ccc|ccc} 1 & 0 & 0 & 1 & 1 & 0 \\ 0 & 1 & 1 & 0 & -1 & 0 \\ 0 & 0 & 1 & 1 & 1 & 1 \end{array} \right) \begin{array}{l} \\ -(III) \\ \end{array} \\ &\rightarrow \left( \begin{array}{ccc|ccc} 1 & 0 & 0 & 1 & 1 & 0 \\ 0 & 1 & 0 & -1 & -2 & -1 \\ 0 & 0 & 1 & 1 & 1 & 1 \end{array} \right) = (I|A^{-1}) \\ &\Rightarrow A^{-1} = \begin{pmatrix} 1 & 1 & 0 \\ -1 & -2 & -1 \\ 1 & 1 & 1 \end{pmatrix}. \end{aligned}$$

**Q5.** (c).

$$A\mathbf{b} = \begin{pmatrix} 1 & 4 \\ 3 & 1 \end{pmatrix} \begin{pmatrix} -8 \\ 6 \end{pmatrix} = \begin{pmatrix} 16 \\ -12 \end{pmatrix} = -2 \begin{pmatrix} -8 \\ 6 \end{pmatrix} = -2\mathbf{b}.$$

**Q6.** (b). We plug  $y_0 = 2$  and  $y_1 = \frac{5}{3}$  into the difference equation (for  $k = 1$ ) and obtain:

$$(1 - a)y_1 + ay_0 - 1 = 0$$

$$\begin{aligned} \Leftrightarrow (1-a) \frac{5}{3} + 2a - 1 &= 0 \\ \Leftrightarrow \frac{5}{3} - \frac{5}{3}a + 2a - 1 &= 0 \\ \Leftrightarrow \frac{1}{3}a &= -\frac{2}{3} \\ \Leftrightarrow a &= -2. \end{aligned}$$

**Q7.** (d). We obtain the normal form of the difference equation:

$$\begin{aligned} 3(y_k - 2y_{k+1}) &= 6 - 7y_k \\ \Leftrightarrow 3y_k - 6y_{k+1} &= 6 - 7y_k \\ \Leftrightarrow -6y_{k+1} &= -10y_k + 6 \\ \Leftrightarrow y_{k+1} &= \frac{5}{3}y_k - 1. \end{aligned}$$

It follows that  $A = \frac{5}{3}$  and  $B = -1$ . Because  $A > 0$  and  $|A| > 1$ , the general solution of the difference equation is monotone and divergent.

**Q8.** (b). The normal form of the difference equation is

$$y_{k+1} = \frac{1+c}{c-2}y_k + \frac{2}{2-c}.$$

The general solution of the difference equation is divergent and oscillating if and only if

$$A = \frac{1+c}{c-2} \leq -1.$$

**Case 1:**  $c > 2$

$$\begin{aligned} 1+c &\leq -c+2 \\ 2c &\leq 1 \\ c &\leq \frac{1}{2}. \end{aligned}$$

Impossible.

**Case 2:**  $c < 2$

$$\begin{aligned} 1+c &\geq -c+2 \\ 2c &\geq 1 \\ c &\geq \frac{1}{2}. \end{aligned}$$

Hence,  $c \in [\frac{1}{2}, 2)$ .